

No.1571B

LB1649

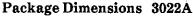
Dual Bidirectional Motor Driver

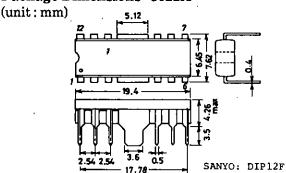
The LB1649 is a dual bidirectional motor driver. Since each channel has a 2-input logic circuit and performs bidirectional driving and braking functions, it is capable of direct driving 2pcs. of motor of various types rated at 6 to 24V. The output voltage can be varied by using external zener diodes. It is especially suited for dual motor drive (reel motor, loading motor, cassette motor in VTR) and for stepping motor drive.

Features

- . With power transistors for motor drive contained, capable of withstanding dash current of 1A max.
- . Performs braking function at the motor stop mode.
- . Contains elements to absorb motor dash current.
- . Input connectable direct to MOS LSI.
- . Minimum number of external parts required.
- . Wide operating voltage range.

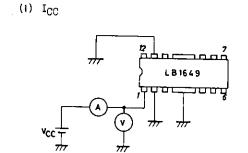
Absolute Maximum Ratings at	unit						
Maximum Supply Voltage	V _{CC} m			25	7	I	
Input Voltage	VIN			25		Į	
Output Current	ī			±1	1	Į	
Allowable Power Dissipati	on Pdma:	x		1.9			
Operating Temperature	Topr		-25 to +75 °C				
Storage Temperature	Tstg		-55 t	0 +125	0(3	
Allowable Operating Conditi	unit						
Supply Voltage	V _{CC}		•	to 25	1	<i>y</i>	
Rlectrical Characteristics	at Ta=2	5°C, V _{CC} =12V, per channel	min	typ	max	unit	
Current Dissipation	ICC	Braking mode, $R_L = \infty$ per channel		7.0 1	0.0	mA	
Output Leakage Current		Braking mode,R _L =∞ per channel		40	120	Au	
Input Threshold Voltage		$R_L = \infty$	0.9	1.05 1	.20	V	
Output Voltage	Λ ^O	$R_L^L = 60 \text{ohms}, V_Z = 7.4 \text{V}$	6.5	7.2	7.5	v	
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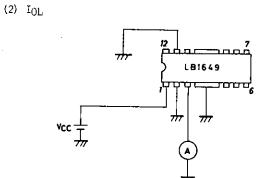




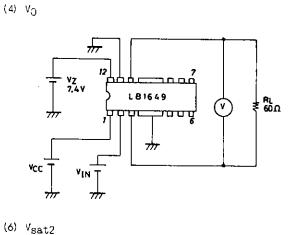
Continued from preceding page. min typ max unit V_{sat1} I_{OUT}=300mA I_{OUT}=500mA V_{sat2} I_{OUT}=300mA I_{OUT}=500mA Output Tr Saturation 1.9 2.3 V Voltage (Upper) 2.0 2.4 V Output Tr Saturation 0.3 0.55 V Voltage (Lower) ٧ 0.5 0.7

Test Circuits (per channel)



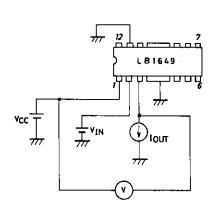


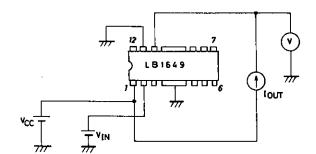
VCC 7 VIN



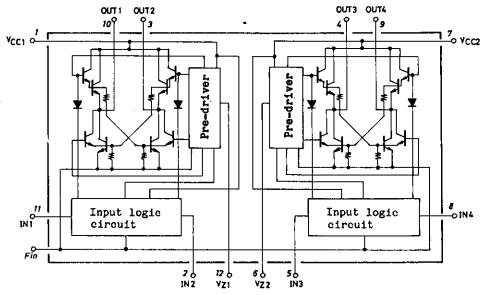


(3) v_{th}





Equivalent Circuit Block Diagram



Truth Table of Logic Circuit

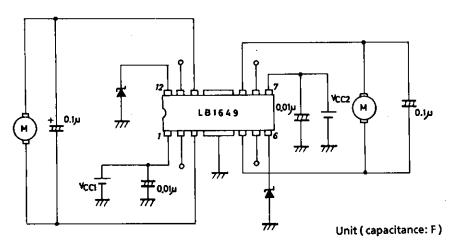
IN1	IN2	OUT1	OUT2	IN3	IN4	OUT3	OUT4
0	0	L	L	0	0	L	L
1	0	H	L	1.	0	H	L
.0	1	L	H	0	1	L	H
1	1	L	L	1	1	L	L

Note) A capacitor of 0.01 μF or greater must be connected across $V_{\rm CC}1$,2 and GND.

	INPUT		OUT PUT				MODE		
IN1	IN2,3	IN4	OUT1	OUT2	OUT3	OUT4	M1	M2	
0	0	0	L	L	L	L	Brake	Brake	
1	0	0	H	Ĺ	L	L	Forward/Reverse	Brake	
0	1	1	L	H	L	L	Reverse/Forward	Brake	
1	1	0	L	L	H	L	Brake	Forward/Reverse	
0	0	1	L	L	L	H	Brake	Reverse/Forward	
1	1	1	L	L	L	L	Brake	Brake	

The remaining input states 1,0,1 and 0,1,0 are not inhibited.

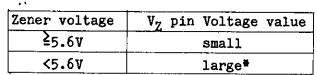
Sample Application Circuit



Input Circuit

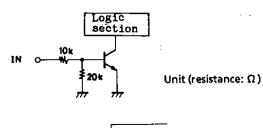
The input circuit is shown right.

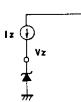
 V_Z pin

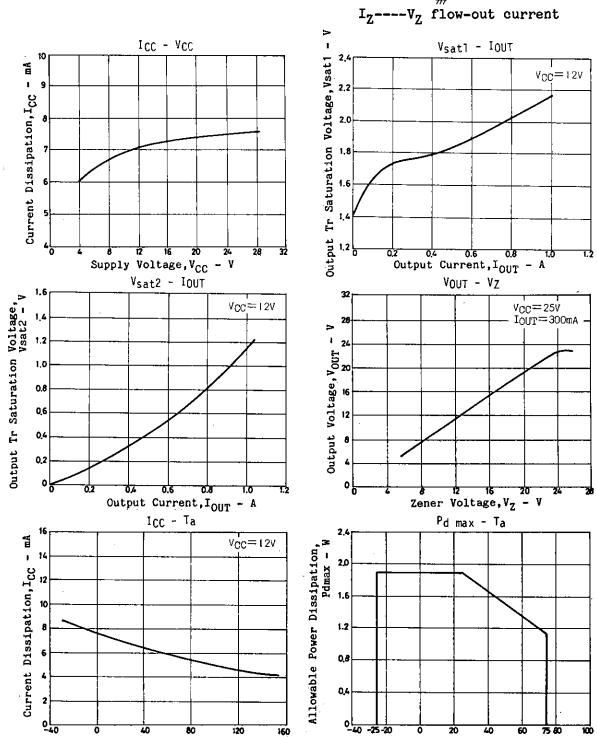


*Susceptible to V_{Z} pin flow-out current change.

Ambient Temperature, Ta - °C







Ambient Temperature, Ta - °C

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